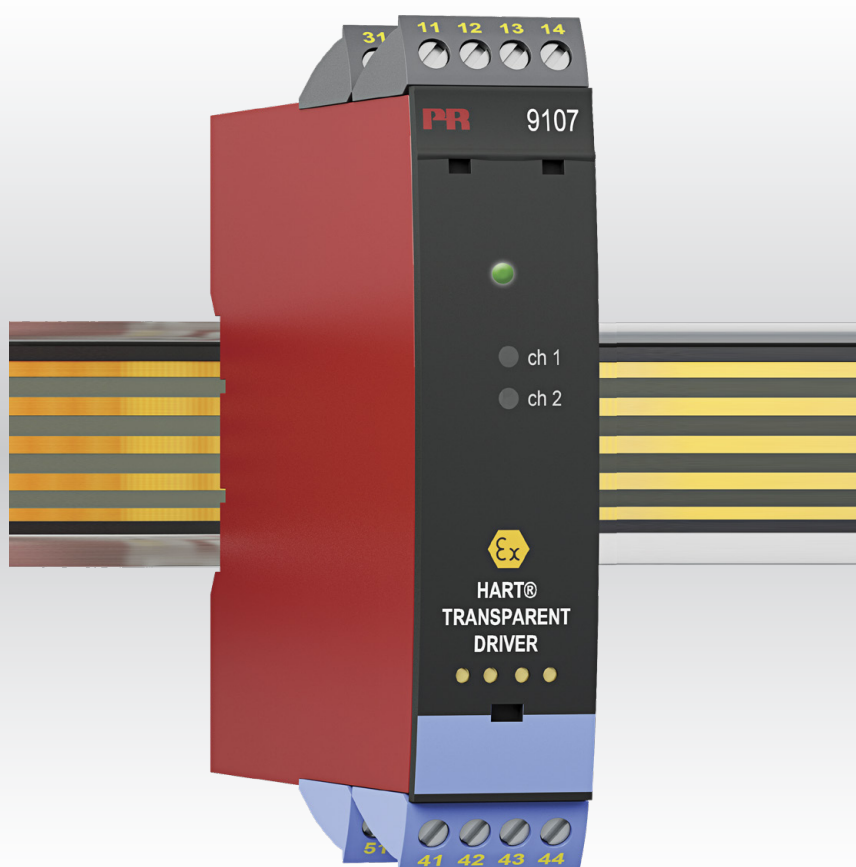


PERFORMANCE  
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# Configuration Manual

## 9107 / 4511

### *Modbus RTU configuration of 9107 HART transparent driver*



TEMPERATURE | I.S. INTERFACES | COMMUNICATION INTERFACES | MULTIFUNCTIONAL | ISOLATION | DISPLAY

No. 9107MCM102-UK  
For 4511 devices from ser. no. 141590001

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# Introduction

## This configuration manual

contains the necessary information for configuring a PR 9107 device which is connected to a PR 4511 Modbus RTU enabler.

## Modbus is a "master-slave" system,

where the "master" communicates with one or multiple "slaves".

The master typically is a PLC (Programmable Logic Controller), DCS (Distributed Control System), HMI (Human Machine Interface), RTU (Remote Terminal Unit) or PC.

The three most common Modbus versions used are: MODBUS ASCII, MODBUS RTU and MODBUS/TCP.

In Modbus RTU, data is coded in binary, and requires only one communication byte per data byte. This is ideal for use over multi-drop RS485 networks, at speeds up to 115,200 bps.

The most common speeds are 9,600 bps and 19,200 bps.

Modbus RTU is the most widely used industrial protocol and is supported by the 4511.

## Modbus RTU

To communicate with a slave device, the master sends a message containing:

### Device Address - Function Code - Data - Error Check

The **Device Address** is a number from 0 to 247.

Messages sent to address 0 (broadcast messages) will be accepted by all slaves, but numbers 1-247 are addresses of specific devices. With the exception of broadcast messages, a slave device always responds to a Modbus message so the master knows the message was received.

## 4511 Supported Modbus Function Codes

Command	Function code
Read Holding Registers*	03
Read Input Registers*	04
Write Single Register	06
Diagnostics	08
Write Multiple Registers	16

\*Holding Registers and Input Registers contain identical data in PR 4511.

The **Function Code** defines the command that the slave device is to execute, such as read data, accept data, report status. Some function codes have sub-function codes.

The **Data** defines addresses in the device's memory map for read functions, contains data values to be written into the device's memory, or contains other information needed to carry out the function requested.

The **Error Check** is a 16-bit numeric value representing the Cyclic Redundancy Check (CRC).

## Maximum number of registers which can be read or written at once

For a read command, the limit is 8 registers at a baud rate up to 38,400 bps, 16 registers @ 57,800 bps and 32 registers @ 115,200 bps.

For a write command, the limit is 123 registers at baud rates up to 115,200 bps.

## 4511 Modbus parameter settings

Automatic Baudrate Detection:	Can be configured YES or <b>NO</b>
Supported baudrates:	2400, 4800, 9600, <b>19.2k</b> , 38.4k, 57.6k, 115.2k bps
Parity Mode:	<b>Even</b> , Odd or None parity
Stop Bits:	<b>1</b> or 2 stop bits
Response delay:	0...1000 ms ( <b>0 ms = default</b> )
Modbus slave addressing range:	1 - 247 ( <b>247 = default address</b> )
Modbus Parameter Storage:	Saved in non-volatile memory in the 4511 device

(Factory Default Values are marked in **bold**)

## Modbus RTU segment line termination

A 120 Ohm resistor should be installed on both ends of a RS485 Modbus RTU segment loop to prevent signal echoes from corrupting data on the line.

## 9107 Configuration Parameter List

Category	Parameter Name	Modbus Address	Register Size	Read/Write	Type	Description	Values
GENERAL	DEVICE NUMBER	0	1	RO	UNSIGNED INTEGER	Defines the actual device number	9107 = 37127 (0x9107)
GENERAL	DEVICE VERSION	1	1	RO	UNSIGNED INTEGER	Product version	0
GENERAL	PASSWORD	2	1	R/W	UNSIGNED INTEGER	Password for entering configuration menu	Range: 0...9999
INPUT	CHANNEL 1 LOW LIMIT	3	1	R/W	UNSIGNED INTEGER	Low limit for loop error detection on channel 1 in 1/10 mA	Range: 0...299
INPUT	CHANNEL 1 HIGH LIMIT	4	1	R/W	UNSIGNED INTEGER	High limit for loop error detection on channel 1 in 1/10 mA	Range: 0...299
INPUT	CHANNEL 2 LOW LIMIT	5	1	R/W	UNSIGNED INTEGER	Low limit for loop error detection on channel 2 in 1/10 mA	Range: 0...299
INPUT	CHANNEL 2 HIGH LIMIT	6	1	R/W	UNSIGNED INTEGER	High limit for loop error detection on channel 2 in 1/10 mA	Range: 0...299
OUTPUT	RAIL ERROR	7	1	R/W	UNSIGNED INTEGER	Set device to indicate on rail when error occurring.	NO = 0 YES = 1
DISPLAY	DISPLAY CONTRAST	8	1	R/W	UNSIGNED INTEGER	Contrast in the LCD display	Range: 0...9
DISPLAY	DISPLAY BACKLIGHT	9	1	R/W	UNSIGNED INTEGER	Backlight intensity in LCD	Range: 0...9
DISPLAY	TAG TEXT CHANNEL 1	10	3	R/W	CHAR ASCII	Tag of the device channel 1 (5 characters)	Range: Ascii values from 32 to 90 (' ' to 'Z')
DISPLAY	TAG TEXT CHANNEL 2	13	3	R/W	CHAR ASCII	Tag of the device channel 2 (5 characters)	Range: Ascii values from 32 to 90 (' ' to 'Z')
DISPLAY	LINE FUNCTION	16	1	R/W	UNSIGNED INTEGER	Information shown in input line of display in monitor mode (normal mode).	LOOP = 0 TAG = 1 ALTERNATING = 2
GENERAL	ENABLE PASSWORD	17	1	R/W	UNSIGNED INTEGER	Password protect entry to configuration menu	NO = 0 YES = 1
GENERAL	HELP TEXT LANGUAGE	18	1	R/W	UNSIGNED INTEGER	Language for the help texts shown on display	UK = 0 DK = 1 DE = 2 FR = 3 SE = 4 IT = 5 ES = 6
GENERAL	DEVICE TYPE	19	1	RO	UNSIGNED INTEGER	Defines the actual device type (1 or 2 channel) (e.g. 9107BA=0xBA)	BA = 42 (0x2A) BB = 43 (0x2B)
GENERAL	CHECKSUM	100	1	RO	UNSIGNED INTEGER	CRC16 checksum of the configuration	Range 0...65536
GENERAL	Configuration counter	101	1	RO	UNSIGNED INTEGER	This counter will count the number of times the configuration has been changed. The counter is reset on power-up	Range 0...65536

## 9107 Process Parameter List

Parameter Name	Register Address	Register Size	Read/Write	Type	Description	Values
DISPLAY VALUE 1	1000	1	RO	INTEGER	Shows the value of channel 1 in 1/10 mA. Accuracy: $\pm 2\%$	-
DISPLAY VALUE 2	1001	1	RO	INTEGER	Shows the value of channel 2 in 1/10 mA. Accuracy: $\pm 2\%$	-
LOOP STATUS	1002	1	RO	UNSIGNED INTEGER	Shows the status of internal errors.	LOOP 1 BROKEN: bit 0 = 1 LOOP 1 UNDER RANGE: bit 1 = 1 LOOP 1 OVER RANGE: bit 2 = 1 UNUSED: bit 3 = 1 LOOP 2 BROKEN: bit 4 = 1 LOOP 2 UNDER RANGE: bit 5 = 1 LOOP 2 OVER RANGE: bit 6 = 1 UNUSED: bit 7 = 1
ERROR STATUS	1003	1	RO	UNSIGNED INTEGER	The calculated output value (in $\mu\text{A}$ or $\mu\text{V}$ ).	RAM ERROR: bit 0 = 1 EEPROM ERROR: bit 1 = 1 CHANNEL 1 ERROR: bit 2 = 1 CHANNEL 2 ERROR: bit 3 = 1 SUPPLY ERROR: bit 4 = 1 FLASH ERROR: bit 5 = 1 INIT ERROR: bit 6 = 1 UNUSED: bit 7
EEPROM Status	1004	1	RO	UNSIGNED INTEGER	Shows the status of the internal EEPROM.	EEPROM 1 OK: bit 0 = 1 EEPROM 2 OK: bit 1 = 1 SET WHILE WRITING EEPROM 1: bit 2 = 1 SET WHILE WRITING EEPROM 2: bit 3 = 1 UNUSED: bit 4...7
OUT STATE	1005	1	R/W	UNSIGNED INTEGER	Controls error out and rail signal.	UNUSED: bit 0...2 ERROR OUT (1 = De-energized, 0 = Energized) bit 3 RAIL SIGNAL (1 = Closed, 0 = Open) bit 4 UNUSED: bit 5...7
VALUE 1	1006	2	RO	FLOAT	The measured value for channel 1 in $\mu\text{A}$ .	
VALUE 2	1008	2	RO	FLOAT	The measured value for channel 2 in $\mu\text{A}$ .	
MEASURE CONTROL	1012	1	R/W	UNSIGNED INTEGER	Controls the various updates of process values and configuration enabling simulation.	NEW CONFIG bit 0 = 1 DISABLE ERROR OUT bit 1 = 1 DISABLE RAIL SIGNAL bit 2 = 1 UNUSED bit 3...7  NOTE: NEW CONFIG reads a new configuration from EEPROM and clears all errors.
TIMEOUT COUNTER	1013	1	RO	UNSIGNED INTEGER	Time-out counter will reset all bits in MEASURE CONTROL when reaching 0. Decrements once every 0.075 s and is by default reset to 133 every 10 seconds effectively disabling simulation. The counter is reset to 10 s by the 9107 when there is successful communication with 4511. Effectively disabling simulation when 4511 is removed.	Range: 0...255

# 4511 Modbus Parameter Lists

## 4511 Modbus Configuration Parameter List

Parameter Name	Register Address	Register Size	Read/Write	Type	Description	Values
ENABLE MODBUS	3000	1	R/W	INTEGER	Enable Modbus communication. If disabled, 4511 ignores all frames sent from the Modbus master and the only way to re-enable Modbus communication is by using the 4511 menu.	NO = 0 YES = 1
BAUDRATE	3001	1	R/W	INTEGER	The baud value used for Modbus communication	2400 BAUD = 0 4800 BAUD = 1 9600 BAUD = 2 19200 BAUD = 3 38400 BAUD = 4 57600 BAUD = 5 115200 BAUD = 6
ENABLE AUTOBAUD	3002	1	R/W	INTEGER	Enable automatic baudrate detection. If enabled, 4511 determines the baudrate automatically by listening to frames sent on the Modbus line.	NO = 0 YES = 1
PARITY	3003	1	R/W	INTEGER	Configures parity check on Modbus frames	NONE = 0 EVEN PARITY = 1 ODD PARITY = 2
STOP BITS	3004	1	R/W	INTEGER	Configures the number of stop bits in Modbus frames	ONE STOP BIT = 1 TWO STOP BITS = 2
ADDRESS	3005	1	R/W	INTEGER	Configures the Modbus address of the 4511 (Address 0 is broadcast address)	Range: 1...247
RESPONSE DELAY	3006	1	R/W	INTEGER	Configures minimum delay for Modbus response in ms	Range: 0...1000

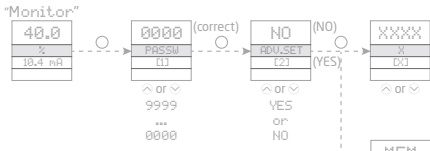
## 4511 Additional Parameter List

Parameter Name	Register Address	Register Size	Read/Write	Type	Description	Values
ROTATE DEVICE	3100	1	R/W	INTEGER	Enables the display and key buttons to be used normally when the host device is mounted upside down	NO = 0 YES = 1

## 4511 Modbus Status Parameter List

Parameter Name	Register Address	Register Size	Read/Write	Type	Description	Values
AUTOBAUD STATUS	4000	1	RO	INTEGER	Actual state of automatic baudrate detection	2400 BAUD = 0 4800 BAUD = 1 9600 BAUD = 2 19200 BAUD = 3 38400 BAUD = 4 57600 BAUD = 5 115200 BAUD = 6 SEARCHING = 7 ERROR = 8
IDENTIFY DEVICE	4001	1	R/W	INTEGER	Enables the device to flash the LCD background with approx. 4 Hz. <b>Value will automatically return to NO if not written within 10 seconds!</b>	NO = 0 YES = 1
MAXIMUM READ REGISTERS	4002	1	RO	INTEGER	Maximum allowed number of registers that can be read in one command, with the given/detected baudrate	Range: 8...32

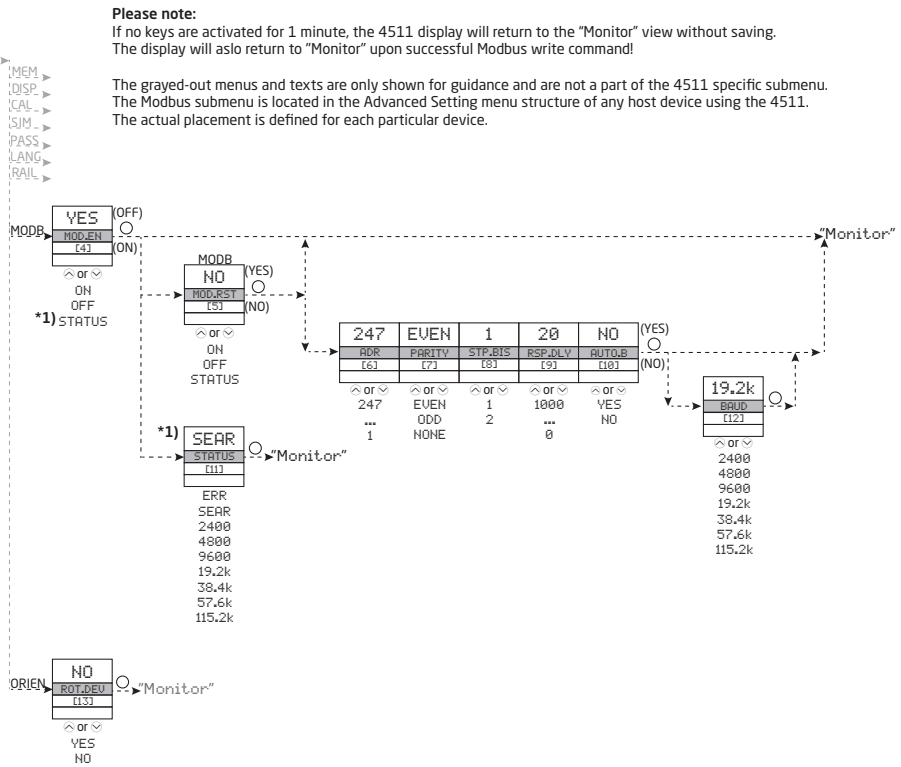
# 4511 Modbus Front Programming Parameter Menu



## Scrolling HELP TEXTS:

- [1] Set correct password
- [2] Enter advanced setup menu
- [3] Perform memory operations  
Enter display setup  
Perform process calibration  
Enter simulation setup  
Enter password setup  
Enter language setup  
Enter rail setup (System 9000)  
Enter Modbus setup
- [4] Check automatic baudrate detection status  
Enable Modbus communication  
Disable Modbus communication
- [5] Reset Modbus to default
- [6] Select Modbus slave address
- [7] Select parity for Modbus
- [8] Select number of stop bits
- [9] Select response delay in ms
- [10] Enable automatic baudrate detection
- [11] Searching for Modbus baudrate  
Modbus baudrate detected  
Modbus baudrate not detected
- [12] Select baudrate in bps
- [13] Rotate device upside down?

\* 1) Only if automatic baudrate detection is enabled





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